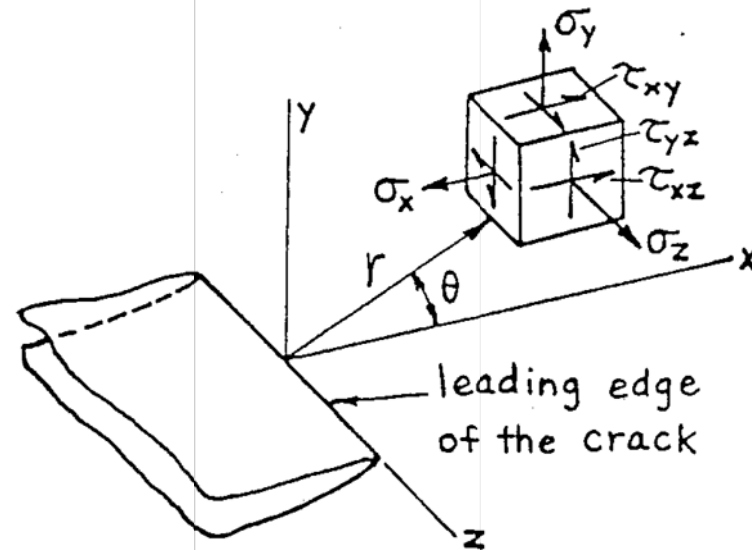


# **Fundamentals of Fracture Mechanics**

- **Evolution from the early work of Griffith (1921)**
- **Fatigue is one of the successful applications of fracture mechanics**
- **Mechanics for the prediction of crack growth**
- **Need to define a crack driving force**
- **Similitude and crack-tip fields**
- **Three modes of loading - Modes I, II and III**

# Linear Elastic Fracture Mechanics

- **Isotropic homogeneous elastic materials assumed**
- **Elastic properties:  $E$ ,  $\nu$ ,  $\kappa = 3 - 4\nu$  (plane strain)**  
 $\kappa = (3 - \nu)/(1 + \nu)$  (plane stress)  
 $G = E / 2(1 + \nu)$
- **Stress and displacement fields w.r.t. crack-tip**  
 $\sigma_{\alpha\beta} = f(r, \theta, K)$   
 $\mu_{\alpha} = f(r, \theta, K)$   
**Hence similitude concept**



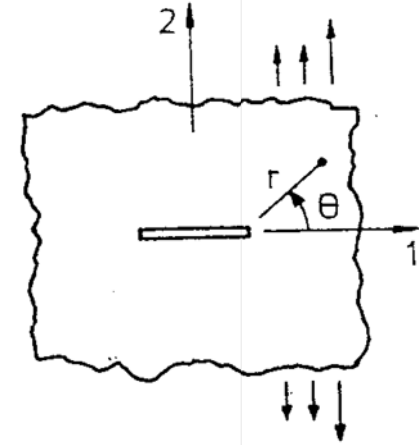
# Mode I Stress and Displacement Fields

- Crack-Tip Stress Fields**

$$\sigma_x = \frac{K_I}{(2\pi r)^{1/2}} \cos \frac{\theta}{2} \left[ 1 - \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \right] + \sigma_{x0} + O(r^{1/2})$$

$$\sigma_y = \frac{K_I}{(2\pi r)^{1/2}} \cos \frac{\theta}{2} \left[ 1 + \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \right] + O(r^{1/2})$$

$$\tau_{xy} = \frac{K_I}{(2\pi r)^{1/2}} \sin \frac{\theta}{2} \cos \frac{\theta}{2} \cos \frac{3\theta}{2} + O(r^{1/2})$$



- Crack-Tip Displacement Fields (Plane Strain with Higher Order Terms Omitted)**

$$\sigma_z = \nu(\sigma_x + \sigma_y), \tau_{xz} = \tau_{yz} = 0$$

$$u = \frac{K_I}{G} [r/(2\pi)]^{1/2} \cos \frac{\theta}{2} \left[ 1 - 2\nu + \sin^2 \frac{\theta}{2} \right]$$

$$v = \frac{K_I}{G} [r/(2\pi)]^{1/2} \sin \frac{\theta}{2} \left[ 1 - 2\nu - \cos^2 \frac{\theta}{2} \right]$$

$$\omega = 0$$

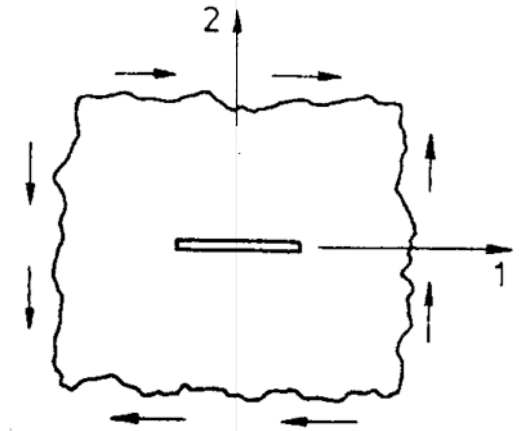
## Mode II Stress and Displacement Fields

- Crack-Tip Stress Fields**

$$\sigma_x = \frac{K_{II}}{(2\pi r)^{1/2}} \sin \frac{\theta}{2} \left[ 2 + \cos \frac{\theta}{2} \cos \frac{3\theta}{2} \right] + \sigma_{x0} + O(r^{1/2})$$

$$\sigma_y = \frac{K_{II}}{(2\pi r)^{1/2}} \sin \frac{\theta}{2} \cos \frac{\theta}{2} \cos \frac{3\theta}{2} + O(r^{1/2})$$

$$\tau_{xy} = \frac{K_{II}}{(2\pi r)^{1/2}} \cos \frac{\theta}{2} \left[ 1 - \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \right] + O(r^{1/2})$$



- Crack-Tip Displacement Fields (Plane Strain with Higher Order Terms Omitted)**

$$\sigma_z = \nu(\sigma_x + \sigma_y), \tau_{xz} = \tau_{yz} = 0$$

$$u = \frac{K_{II}}{G} [r/(2\pi)]^{1/2} \sin \frac{\theta}{2} \left[ 2 - 2\nu + \cos^2 \frac{\theta}{2} \right]$$

$$v = \frac{K_{II}}{G} [r/(2\pi)]^{1/2} \cos \frac{\theta}{2} \left[ -1 + 2\nu - \sin^2 \frac{\theta}{2} \right]$$

$$\omega = 0$$

## Mode III Stress and Displacement Fields

- **Crack-Tip Stress Fields**

$$\tau_{xz} = \frac{K_{III}}{(2\pi r)^{1/2}} \sin \frac{\theta}{2} + \tau_{xz0} + O(r^{1/2})$$

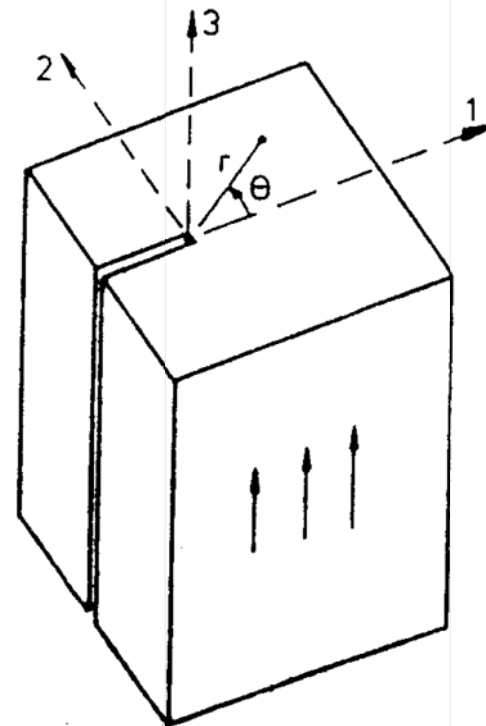
$$\tau_{yz} = \frac{K_{III}}{(2\pi r)^{1/2}} \cos \frac{\theta}{2} + O(r^{1/2})$$

$$\sigma_x = \sigma_y = \sigma_z = \tau_{xy} = 0$$

- **Crack-Tip Displacement Fields (Plane Strain with Higher Order Terms Omitted)**

$$\omega = \frac{K_{III}}{G} [(2r)/\pi]^{1/2} \sin \frac{\theta}{2}$$

$$\mu = \nu = 0$$

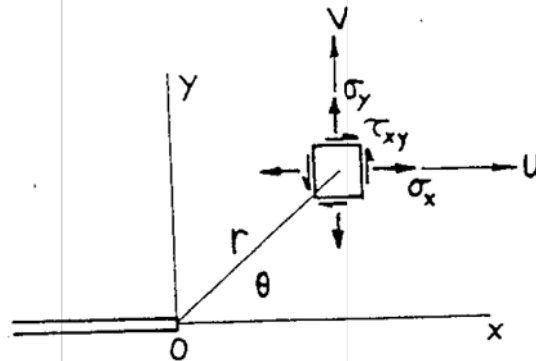


# Alternate Expressions Crack-Tip Stress & Displacement Fields (X - Y Components)

## Mode I

$$\begin{Bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{Bmatrix} = \frac{K_I}{\sqrt{2\pi r}} \cos \frac{\theta}{2} \begin{Bmatrix} 1 - \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \\ 1 + \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{3\theta}{2} \end{Bmatrix} = \frac{K_I}{\sqrt{2\pi r}} \frac{1}{4} \begin{Bmatrix} 3 \cos \frac{\theta}{2} + \cos \frac{5\theta}{2} \\ 5 \cos \frac{\theta}{2} - \cos \frac{5\theta}{2} \\ -\sin \frac{\theta}{2} + \sin \frac{5\theta}{2} \end{Bmatrix}$$

$$\begin{Bmatrix} u \\ v \end{Bmatrix} = \frac{K_I}{G} \sqrt{\frac{r}{2\pi}} \begin{Bmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{Bmatrix} \left( \beta - \cos^2 \frac{\theta}{2} \right) = \frac{K_I}{G} \sqrt{\frac{r}{2\pi}} \frac{1}{4} \begin{Bmatrix} (4\beta - 3) \cos \frac{\theta}{2} - \cos \frac{3\theta}{2} \\ (4\beta - 1) \sin \frac{\theta}{2} - \sin \frac{3\theta}{2} \end{Bmatrix}$$



## Mode II

$$\begin{aligned} \begin{Bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{Bmatrix} &= \frac{K_{II}}{\sqrt{2\pi r}} \begin{Bmatrix} -\sin \frac{\theta}{2} \left( 2 + \cos \frac{\theta}{2} \cos \frac{3\theta}{2} \right) \\ \sin \frac{\theta}{2} \cos \frac{\theta}{2} \cos \frac{3\theta}{2} \\ \cos \frac{\theta}{2} \left( 1 - \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \right) \end{Bmatrix} = \frac{K_{II}}{\sqrt{2\pi r}} \frac{1}{4} \begin{Bmatrix} -5 \sin \frac{\theta}{2} - \sin \frac{5\theta}{2} \\ -\sin \frac{\theta}{2} + \sin \frac{5\theta}{2} \\ 3 \cos \frac{\theta}{2} + \cos \frac{5\theta}{2} \end{Bmatrix} \\ \begin{Bmatrix} u \\ v \end{Bmatrix} &= \frac{K_{II}}{G} \sqrt{\frac{r}{2\pi}} \begin{Bmatrix} \sin \frac{\theta}{2} \left( \beta + \cos^2 \frac{\theta}{2} \right) \\ -\cos \frac{\theta}{2} \left( \beta - 2 + \cos^2 \frac{\theta}{2} \right) \end{Bmatrix} = \frac{K_{II}}{G} \sqrt{\frac{r}{2\pi}} \frac{1}{4} \begin{Bmatrix} (4\beta + 1) \sin \frac{\theta}{2} - \sin \frac{3\theta}{2} \\ -(4\beta - 5) \cos \frac{\theta}{2} + \cos \frac{3\theta}{2} \end{Bmatrix} \end{aligned}$$

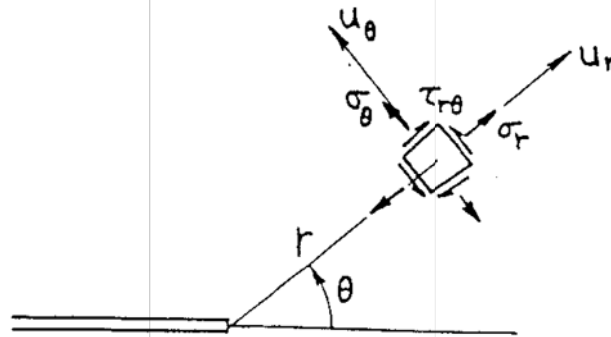
where  $\beta (= 1/\alpha) = \begin{cases} 2(1-\nu) \cdot \text{plane} \cdot \text{strain} \\ 2 \left( \frac{1}{1+\nu} \right) \cdot \text{plane} \cdot \text{stress} \end{cases}$

## Alternate Expressions For Crack-Tip Stress and Displacement Fields (r - $\theta$ Components)

### Mode I

$$\begin{Bmatrix} \sigma_r \\ \sigma_\theta \\ \tau_{r\theta} \end{Bmatrix} = \frac{K_I}{\sqrt{2\pi r}} \cos \frac{\theta}{2} \begin{Bmatrix} 1 + \sin^2 \frac{\theta}{2} \\ \cos^2 \frac{\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{\theta}{2} \end{Bmatrix} = \frac{K_I}{\sqrt{2\pi r}} \frac{1}{4} \begin{Bmatrix} 5 \cos \frac{\theta}{2} - \cos \frac{3\theta}{2} \\ 3 \cos \frac{\theta}{2} + \cos \frac{3\theta}{2} \\ \sin \frac{\theta}{2} + \sin \frac{3\theta}{2} \end{Bmatrix}$$

$$\begin{Bmatrix} u_r \\ u_\theta \end{Bmatrix} = \frac{K_I}{G} \sqrt{\frac{r}{2\pi}} \begin{Bmatrix} \cos \frac{\theta}{2} \\ -\sin \frac{\theta}{2} \end{Bmatrix} \left( \beta - \cos^2 \frac{\theta}{2} \right) = \frac{K_I}{G} \sqrt{\frac{r}{2\pi}} \frac{1}{4} \begin{Bmatrix} (4\beta - 3) \cos \frac{\theta}{2} - \cos \frac{3\theta}{2} \\ -(4\beta - 1) \sin \frac{\theta}{2} + \sin \frac{3\theta}{2} \end{Bmatrix}$$





## Mode II

$$\begin{Bmatrix} \sigma_r \\ \sigma_\theta \\ \tau_{r\theta} \end{Bmatrix} = \frac{K_{II}}{\sqrt{2\pi r}} \begin{Bmatrix} \sin \frac{\theta}{2} \left( 1 - 3 \sin^2 \frac{\theta}{2} \right) \\ -\sin \frac{\theta}{2} 3 \cos^2 \frac{\theta}{2} \\ \cos \frac{\theta}{2} \left( 1 - 3 \sin^2 \frac{\theta}{2} \right) \end{Bmatrix} = \frac{K_{II}}{\sqrt{2\pi r}} \frac{1}{4} \begin{Bmatrix} -5 \sin \frac{\theta}{2} + 3 \sin \frac{3\theta}{2} \\ -3 \sin \frac{\theta}{2} - 3 \sin \frac{3\theta}{2} \\ \cos \frac{\theta}{2} + 3 \cos \frac{3\theta}{2} \end{Bmatrix}$$

$$\begin{Bmatrix} u_r \\ u_\theta \end{Bmatrix} = \frac{K_{II}}{G} \sqrt{\frac{r}{2\pi}} \begin{Bmatrix} -\sin \frac{\theta}{2} \left( \beta - 3 \cos^2 \frac{\theta}{2} \right) \\ -\cos \frac{\theta}{2} \left( \beta + 2 - 3 \cos^2 \frac{\theta}{2} \right) \end{Bmatrix} = \frac{K_{II}}{G} \sqrt{\frac{r}{2\pi}} \frac{1}{4} \begin{Bmatrix} -(4\beta - 3) \sin \frac{\theta}{2} + 3 \sin \frac{3\theta}{2} \\ -(4\beta - 1) \cos \frac{\theta}{2} + 3 \cos \frac{3\theta}{2} \end{Bmatrix}$$

where  $\beta (= 1/\alpha) = \begin{cases} 2(1 - \nu) \cdot \text{plane} \cdot \text{strain} \\ 2 \left( \frac{1}{1 + \nu} \right) \cdot \text{plane} \cdot \text{stress} \end{cases}$

**Note:** For Mode I,  $u_r = u, u_\theta = -v$  (Displacement is in  $\theta/2$  direction)

## Relationships Between G and K

- **Total energy release rate in general subdivided for each mode**

$$G = G_I + G_{II} + G_{III}$$

where

$$G_I = K_I^2 / E'$$

$$G_{II} = K_{II}^2 / E'$$

$$G_{III} = K_{III}^2 / 2G = \frac{1+\nu}{E} K_{III}^2$$

- **Above relationships apply mainly to straight cracks**
- **Different relationships needed for anisotropic bodies (Tada, Paris & Irwin, 1985)**

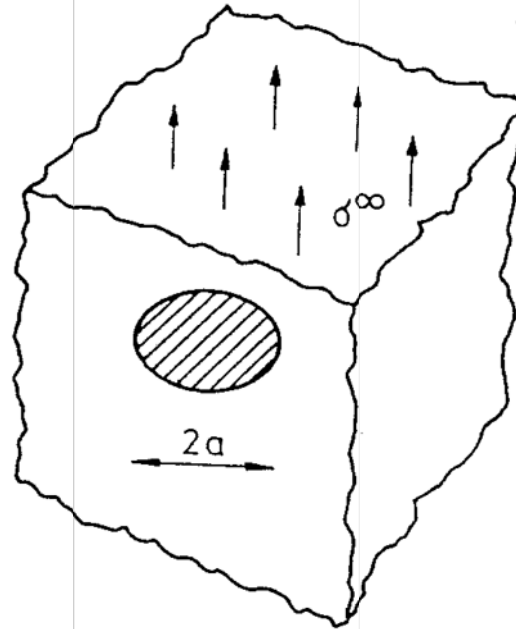
## **Catalogs/Sources of Stress Intensity Factor Solutions**

- **Stress Analysis of Cracks handbook (Tada, Paris & Irwin, 1985)**
- **SURFCAN1 Software (Through-Thickness/Semi-Elliptical Cracks)**
- **Other Handbooks By**
  - **Sih**
  - **Murakami**
  - **Rooke and Cartwright**

## Typical Specimen Geometries (Cont.)

**Penny shaped crack, Near crack edge fields are identical to Mode I plane strain**

$$K_I = \frac{2}{\pi} \sigma^\infty \sqrt{\pi a}$$



# Energy Release Rate and Load Induced Displacement

- Consider Mode I problem with load  $P$  per unit thickness

$PE$  = potential energy per unit thickness

$\Delta$  = load point displacement

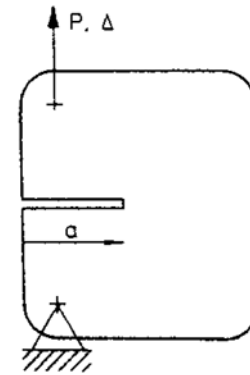
$G$  = energy release rate per unit thickness

$$G = -\left(\frac{\partial PE}{\partial a}\right)_P$$

- For a prescribed  $P$

$$PE = SE - P\Delta = \frac{1}{2}P\Delta - P\Delta = -\frac{1}{2}P\Delta$$

$$G = \frac{1}{2} \frac{\partial}{\partial a} (P\Delta) \Big|_P = \frac{P}{2} \left(\frac{\partial \Delta}{\partial a}\right)_P$$



## Compliance Analysis of Loaded Specimen

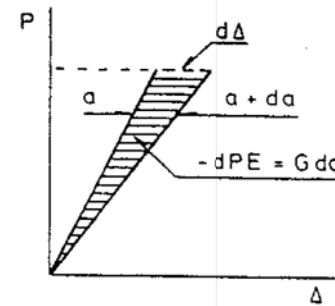
- **Definition of compliance  $C = \Delta/P$**

where  $C$  depends only on geometry,  $E$  and  $\nu$

$$\left(\frac{\partial \Delta}{\partial a}\right)_P = P \frac{dc}{da}$$

$$\text{and } G = \frac{P}{2} \left(\frac{\partial \Delta}{\partial a}\right)_P$$

$$\text{Hence } G = \frac{P^2}{2} \frac{dc}{da}$$



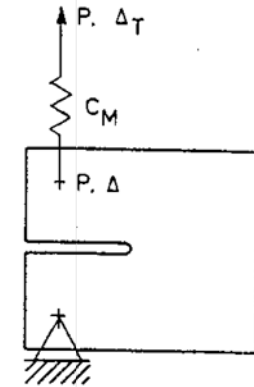
## Effects of Machine Compliance

- $C_M =$  Machine compliance (testing machine)
- $C_M$  in series with specimen
- $\Delta_T = \Delta + C_M P = \Delta + (C_M / C)\Delta =$  total displacement

- $$PE = SE + \frac{1}{2} C_M P^2 = \frac{1}{2} C^{-1} \Delta^2 + \frac{1}{2} C_M^{-1} (\Delta_T - \Delta)^2$$

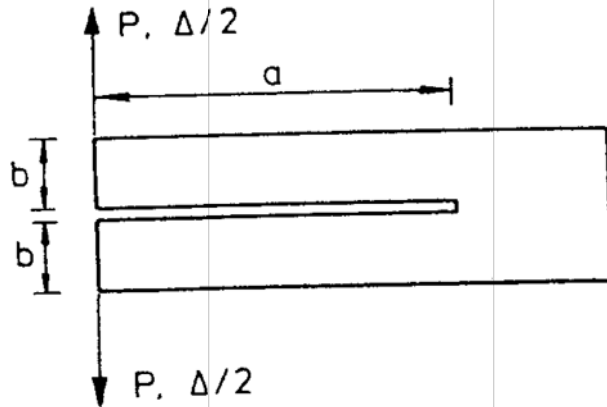
- $$G = -\left(\frac{\partial PE}{\partial a}\right)_{\Delta_T} = -\left[C^{-1} \Delta - C_M^{-1} (\Delta_T - \Delta)\right] \left(\frac{\partial \Delta}{\partial a}\right)_{\Delta_T} + \frac{1}{2} C^{-2} \Delta^2 \frac{dc}{da}$$

$$= \frac{1}{2} C^{-2} \Delta^2 \frac{dc}{da} = \frac{1}{2} P^2 \frac{dc}{da}$$



## Energy Method For Estimating G and K

- **Double Cantilever Example**



**Treat each arm of specimen as cantilever beam**

$$\frac{\Delta}{2} = \frac{Pa^3}{3EI} = \frac{4Pa^3}{Eb^3}$$

**Hence**

$$C = \frac{8a^3}{Eb^3}$$

$$G = \frac{12P^2a^2}{Eb^3}$$

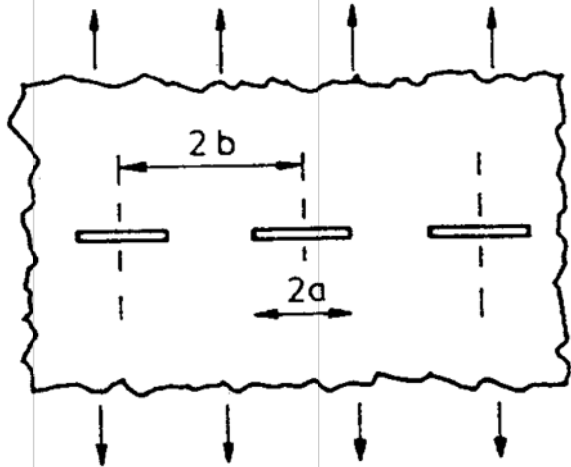
$$K = 2\sqrt{3}P_a b^{-3/2}$$



# Typical Specimen Geometries (Cont.)

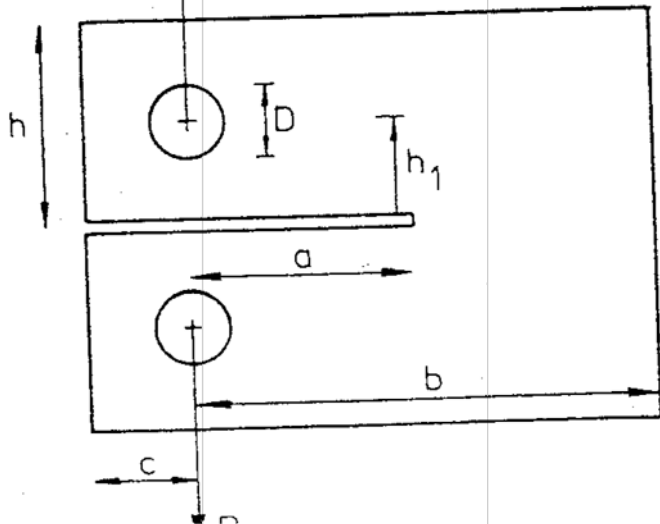
## Line of cracks in tension (also Mode III)

$$K_I = \sigma^\infty \sqrt{\pi a} \left[ \frac{2b}{\pi a} \tan \left( \frac{\pi a}{2b} \right) \right]^{\frac{1}{2}}$$



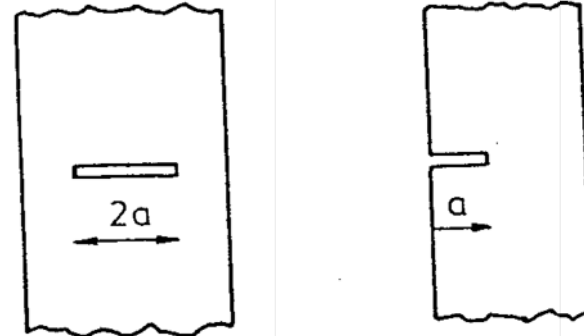
standard ASTM compact tension specimen

$$K_I = (P/b) \sqrt{a} F_1(a/b)$$



## Cracks in finite width strips in Mode III

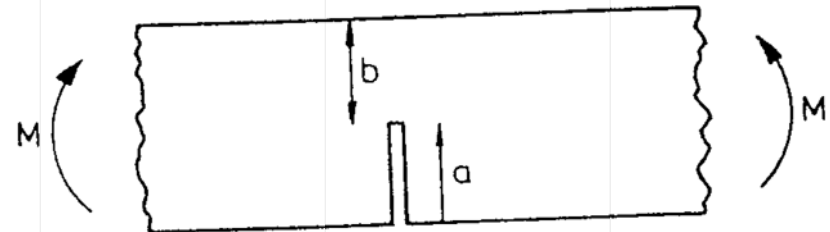
$$K_{III} = \tau^\infty \sqrt{\pi a} \left[ \frac{2b}{\pi a} \tan \left( \frac{\pi a}{2b} \right) \right]^{\frac{1}{2}}$$



## Edge crack in strip in bending

M = moment/thickness

$$K_I = Mb^{-3/2} f(a/b)$$



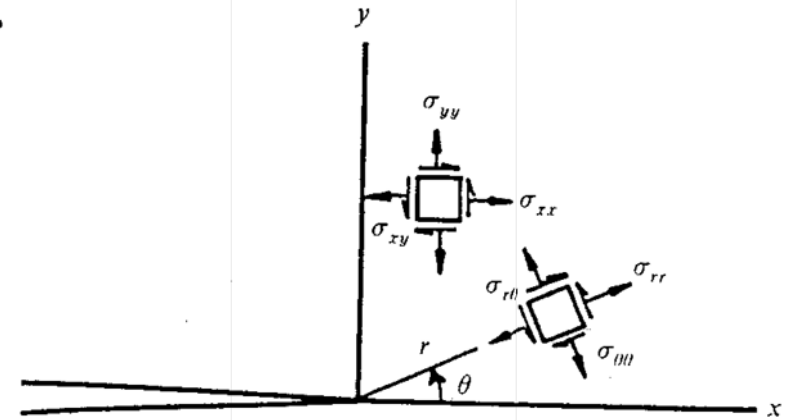
# Derivation of Near-tip Fields Based on Mode I Linear Elastic Fatigue Cracks

The equilibrium equations in polar coordinates are:

$$\begin{aligned} \frac{\partial \sigma_{rr}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{r\theta}}{\partial \theta} + \frac{\sigma_{rr} - \sigma_{\theta\theta}}{r} &= 0, \\ \frac{\partial \sigma_{r\theta}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{\theta\theta}}{\partial \theta} + \frac{2\sigma_{r\theta}}{r} &= 0, \end{aligned} \quad (1)$$

where  $r$  and  $\theta$  are the polar coordinates.

$$\begin{aligned} \epsilon_{rr} &= \frac{\partial u_r}{\partial r}, \\ \epsilon_{\theta\theta} &= \frac{u_r}{r} + \frac{1}{r} \frac{\partial u_\theta}{\partial \theta}, \\ \epsilon_{r\theta} &= \left[ \frac{1}{r} \frac{\partial u_r}{\partial \theta} + \frac{\partial u_\theta}{\partial r} - \frac{u_\theta}{r} \right] \times \left( \frac{1}{2} \right). \end{aligned}$$



The condition of strain compatibility :

$$\frac{\partial^2 \epsilon_{\theta\theta}}{\partial r^2} + \frac{2}{r} \frac{\partial \epsilon_{\theta\theta}}{\partial r} - \frac{1}{r} \frac{\partial^2 \epsilon_{r\theta}}{\partial r \partial \theta} - \frac{1}{r^2} \frac{\partial \epsilon_{r\theta}}{\partial \theta} + \frac{1}{r^2} \frac{\partial \epsilon_{rr}^2}{\partial \theta^2} - \frac{1}{r} \frac{\partial \epsilon_{rr}}{\partial r} = 0. \quad (2)$$

**Hooke's law for plane stress** ( $\sigma_{zz} = 0$ ),

$$E\epsilon_{rr} = \sigma_{rr} - \nu\sigma_{\theta\theta},$$

$$E\epsilon_{\theta\theta} = \sigma_{\theta\theta} - \nu\sigma_{rr},$$

$$2\mu\epsilon_{r\theta} = \mu\gamma_{r\theta} = \sigma_{r\theta},$$

**where  $\mu$  is the shear modulus and, for plane strain** ( $\epsilon_{zz} = 0$ ),

$$2\mu\epsilon_{rr} = (1 - \nu)\sigma_{rr} - \nu\sigma_{\theta\theta},$$

$$2\mu\epsilon_{\theta\theta} = (1 - \nu)\sigma_{\theta\theta} - \nu\sigma_{rr},$$

$$2\mu\epsilon_{r\theta} = \sigma_{r\theta}.$$

**The equilibrium Eqs. (1) are satisfied when the stress components are expressed by the Airy stress function  $\chi$  through**

$$\sigma_{rr} = \frac{1}{r} \frac{\partial \chi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \chi}{\partial \theta^2},$$

$$\sigma_{\theta\theta} = \frac{\partial^2 \chi}{\partial r^2},$$

$$\sigma_{r\theta} = -\frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial \chi}{\partial \theta} \right).$$

The compatibility condition Eq. (2) when expressed in terms of the Airy stress function, satisfies the biharmonic equation,

$$\nabla^2 (\nabla^2 \chi) = 0,$$

where

$$\nabla^2 \equiv \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}$$

is the polar Laplacian.

The boundary conditions are:

$$\sigma_{\theta\theta} = \sigma_{r\theta} = 0 \quad \text{for } \theta = \pm\pi.$$

A possible form of  $\chi$  which accounts for singular stresses at the crack and is single-valued :

$$\chi = r^2 p(r, \theta) + q(r, \theta),$$

where  $p$  and  $q$  are harmonic functions of  $r$  and  $\theta$  which satisfy the Laplace equations

$$\nabla^2 p = 0 \quad \text{and} \quad \nabla^2 q = 0.$$

**Consider solutions of separable form for the Airy stress function,**

$\chi = R(r)\Theta(\theta)$ , **Based on**

$$p = A_1 r^\lambda \cos \lambda \theta + A_2 r^\lambda \sin \lambda \theta,$$

$$q = B_1 r^{(\lambda+2)} \cos (\lambda + 2)\theta + B_2 r^{(\lambda+2)} \sin (\lambda + 2)\theta,$$

**which lead to**

$$\begin{aligned} \chi = r^{(\lambda+2)} [A_1 \cos \lambda \theta + B_1 \cos (\lambda + 2)\theta] \\ + r^{(\lambda+2)} [A_2 \sin \lambda \theta + B_2 \sin (\lambda + 2)\theta]. \end{aligned}$$

**Model I fields:**

$$\sigma_{\theta\theta} = \frac{\partial^2 \chi}{\partial r^2} = (\lambda + 2) (\lambda + 1) r^\lambda [A_1 \cos \lambda \theta + B_1 \cos (\lambda + 2)\theta],$$

$$\sigma_{r\theta} = -\frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial \chi}{\partial \theta} \right)$$

$$= (\lambda + 1) r^\lambda [\lambda A_1 \sin \lambda \theta + (\lambda + 2) B_1 \sin (\lambda + 2)\theta].$$

**Applying the boundary conditions, obtains**

$$(A_1 + B_1) \cos \lambda\pi = 0,$$
$$[\lambda A_1 + (\lambda + 2)B_1] \sin \lambda\pi = 0.$$

**(i)  $\cos \lambda\pi = 0$**

$$\lambda = \frac{2Z + 1}{2}, \quad B_1 = -\frac{\lambda}{\lambda + 2} A_1,$$

**where  $Z$  is an integer including zero.**

**(ii)  $\sin \lambda\pi = 0$**

$$\lambda = Z \quad \text{and} \quad B_1 = -A_1.$$

**Hence**  $\lambda = \frac{Z}{2},$

**where  $Z$  is a positive or negative integer, including zero.**

$$\phi = \frac{1}{2} \sigma_{ij} \epsilon_{ij} \sim r^{2\lambda}.$$

**where  $\phi$  is the strain energy density.**